#### Formal Representation and Automated Transformation of Geometric Statements

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#### **Outline**

- Motivation
- Geometry Programming Language
- Geometric Statement Simplification
- 4 Implementation
- 6 Conclusion and Future Work



# Start with Geometry Software

Geometry problems (drawing or proving) are specified by applying similar (or same) concepts which are implemented differently in these systems.

Table: Constructive style

Cinderella	GeoGebra
Perpendicular(a;A)	PerpendicularLine[A,a]
Circumcircle(A;B;C)	Circle[A,B,C]
AngleBisector(m;n;A)	AngleBisector[m,n]

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parallel(A,B,C,D)	parallel A B C D



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The constructions and predicates can be viewed as concepts.



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- Intergeo project offers a common file format for specifying dynamic diagrams. However, the format only works for constructive style.
- GeoCode is a generic proof scheme standard providing routine codes that can be interfaced with different CAS or provers for proving and DGS for drawing.



#### More — Macro Constructions

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It is needed to standardize macro constructions so that one can specify problems in terms of customized concepts by defining macros.



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• GEOTHER provides a standard form for specifying the entries contained in the predicates routines. However, defined predicates are independent with each other.



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#### Related work

- GEOTHER provides a standard form for specifying the entries contained in the predicates routines. However, defined predicates are independent with each other.
- GeoCode provides the facility for users to define new functions in terms of exited functions. However, these functions are defined only in the constructive style.



# **Objectives**

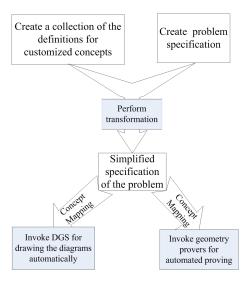
 A general geometry programming language is needed in which one can easily and naturally define geometric concepts and specify problems in terms of the customized concepts (for both constructive and constraint type).



### **Objectives**

- A general geometry programming language is needed in which one can easily and naturally define geometric concepts and specify problems in terms of the customized concepts (for both constructive and constraint type).
- The facility is needed for transforming the specified problems into the ones that target systems can identify and manipulate via specific interfaces

#### Idea





#### Idea

Create a collection of the Create problem definitions for specification customized concepts Perform transformation Simplified specification of the problem Concepting Mapping 1 Invoke DGS for Invoke geometry drawing the diagrams provers for automatically automated proving



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- Built-in concepts:
  - Constants:  $0, \pi$ , etc.
  - Pointers (labels): A, B, l, etc.
  - Types: Point, Line, Segment, Length, Degree, Number, Boolean, etc.
  - Algebra concepts: times, plus, sin, squre, etc.
  - Set concepts: list, choose, ismember, etc.
  - Logic concepts: and, or, not.

### Formalization of Geometric Concepts

• **Abstract concepts**: *A* ::Point, *l* ::Line, *t* ::Triangle, etc.



# Formalization of Geometric Concepts

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- Entity concepts:
  - Geometric objects: intersection(l::Line,m::Line), perpendicularline(A::Point,l::Line), circumcenter(triangle(A::Point,B::Point,C::Point)), etc.
  - **Geometric quantities**: length(segment(A::Point,B::Point)), ratio(a::GeometricQuantity,b::GeometricQuantity), etc.

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  - Geometric quantities: length(segment(A::Point,B::Point)), ratio(a::GeometricQuantity,b::GeometricQuantity), etc.
- Boolean concepts:
  - Geometric relations: parallel(l::Line,m::Line), isin(A::Point,o::Circle), tangent(o::Circle, p::Circle) etc.
  - Quantity relations: lt(a::Length,b::Length), equal(c::Degree,d::Degree), etc.

### **Constructing Geometric Clauses**

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- **Reference clauses**: *A*:=point(), *P*:=intersection(*l*,*m*), etc.
- Boolean clauses: perpendicular(l,m), incident(A,l), etc.
- Compound clauses:
  - Nesting: collinear(foot(D,line(A,B)),foot(D,line(A,C)),foot(D,line(B,C)));
  - **Give**: give(triangle(*A*,*B*,*C*));
  - Configuration: configuration(E:=intersection(line(A,B),line(C,D)),
     F:=intersection(line(A,C),line(B,D)));
  - Declare: declare(A::Point,B::Point,l::Line);
  - Logic: and(parallel(l,m),incident(A,l));
  - List: {A;B;C},{point();point();midpoint(segment(A,B))};
  - **Set**: choosediff(*A*;*B*;*C*,2));
  - Algebra: times(2,length(segment(A,B))).

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#### For example,

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- Definition(intersection(l::Line,m::Line), [A::Point where and(incident(A,l), incident(A,m))], intersect(l,m)
- Definition(completequadrilateral(A::Point,B::Point,C::Point,D::Point, E::Point,F::Point), [configuration(E:=intersection(line(A,B),line(C,D)), F:=intersection(line(A,C),line(B,D)))], null)

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- Definition(diagonal(completequadrilateral(A::Point,B::Point,C::Point,D::Point, E::Point,F::Point)),{[segment(A,D)];[segment(B,C)]; [segment(E,F)]}, null)

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   show(collinear(foot(D, line(A,B)), foot(D, line(A,C)), foot(D, line(B,C)))))
- Problem(Pappus,Theorem,assume(declare(C::Point,F::Point,P::Point, Q::Point,R::Point),A:=point(),B:=point(),D:=point(),E:=point(), give(Pappus(A,B,C,D,E,F,P,Q,R))), show(collinear(P,Q,R)))

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#### Clause Simplification

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- $\bullet Def_4$ : intersection(l::Line,m::Line)  $\triangleq$  [A::Point **where** incident(A,l)  $\land$  incident(A,m)]
- > foot $(D, \text{line}(E,F)) \xrightarrow{Def_1} \text{foot}(D, \text{line}(E,F)) \xrightarrow{Def_2} \text{substitution}$

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- $\gg$  foot(D,line(E,F))  $\xrightarrow{Def_1}$  foot(D,line(E,F))  $\xrightarrow{Def_2}$  substitution

[intersection(perpendicularline(D,line(E,F)),line(E,F))]  $\xrightarrow[substitution]{Def_3,Def_4}{substitution}$  [ $var_1$ ::Point **where** incident(D, $var_0$ )  $\land$  perpendicular( $var_0$ ,line(E,F))  $\land$  incident( $var_1$ , $var_0$ )  $\land$  incident( $var_1$ ,line(E,F))]

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•Def_1: line(A::Point,B::Point) \triangleq l::Line
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$$>$$
 (foot( $D$ ,line( $E$ , $F$ ))  $\xrightarrow{Def_1}$  foot( $D$ ,line( $E$ , $F$ ))  $\xrightarrow{Def_2}$  substitution

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We adopt eager (inner most) strategy to deal with the nesting cases.

### Statement Simplification

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$$\xrightarrow{definitions}$$

$$simplification$$

Problem(Simson,Theorem,assume(declare( $var_0$ ::Point, $var_1$ ::Point, $var_2$ ::Line,  $var_3$ ::Point, $var_4$ ::Line, $var_5$ ::Point, $var_6$ ::Line, $var_7$ ::Point), A:=point(),B:=point(),C:=point(),D:=point(),equal(distance( $var_0$ ,D),distance( $var_0$ , $var_1$ )),equal(distance( $var_0$ , $var_1$ ))))

We use type matching to select the "correct" definitions for simplifying instances.



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Table: Context table for the current statement

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l	perpendicularline $(A, line(C, D))$

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#### Type for instance

Type(foot(D,line(A,B))) = foot(point(),line(point(),point())) Type(intersection(l,line(C,D))) =

intersection(perpendicularline(point(),line(point(),point())),line(point(),point()))

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#### Type for concept

Type(foot(A::Point,l::Line)) = foot(Point,Line)
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Generally, type for instance is not equal to type for concept. How to match them?

Geometry definitions indicate the order of types. We define type upgrade to match types.

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#### Example

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#### Type Matching Rule

Let I and C be an instance and a concept, if  $\mathrm{Type}(I) \leq \mathrm{Type}(C)$ , then the definition of C can be used to simplify instance I.

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[I where constraint context configuration with nondegeneracyCondition]

The simplified instances will be normalized into this form at each step of simplification process.

# **Analysis**

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#### Usability

The simplified problem specifications can be interfaced with Geometry software systems.

#### More Demo

Reuse definitions and problem specifications.

► Pappus,completeQuandrilateral,197,198

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Reuse definitions and problem specifications.

➤ Pappus,completeQuandrilateral,197,198

Dealing with multiple returns.

• example90, 180

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XML based;



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- JDIC package: JDesktop Integration Components;
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#### Conclusion

We have presented a geometry programming language for specifying geometric concepts, definitions, and problems.

The specifications are

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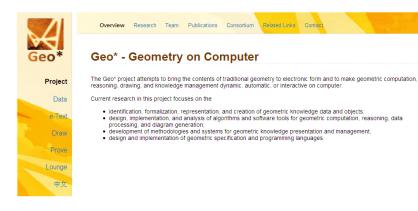
- encoded easily and naturally;
- used in both constraint and constructive cases;
- transformed into ones that can be interfaced with available geometry software systems.

#### **Future Work**

The geometry programming language is still at a preliminary stage. The following problems should be considered further.

- prove the correctness of transformation;
- transform the specifications in this language into natural language and the other way round;
- transform the specifications in this language into algebraic counterparts and interface with CAS.

### Geo\* - Geometry on Computer



Welcome to visit our project home at <a href="http://geo.cc4cm.org/">http://geo.cc4cm.org/</a>

# Thanks!